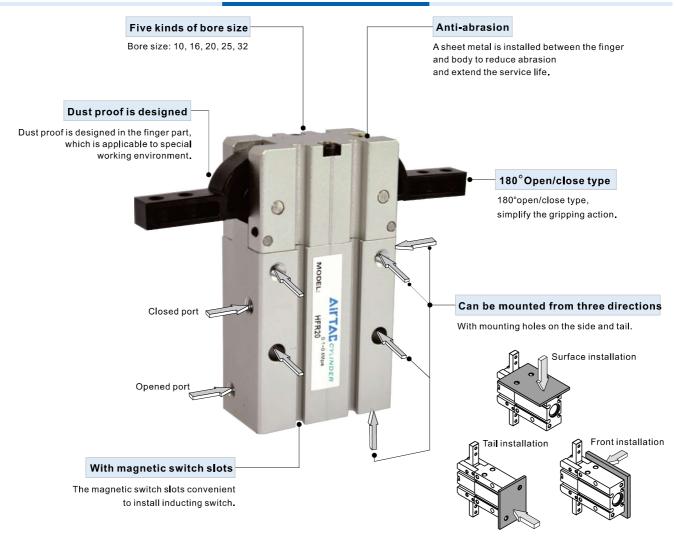


Air gripper——HFR Series

180° open/close style

Compendium of HFR Series



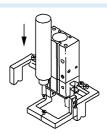
Bore size (mm)	10	16	20	25	32
Acting type	Double acting				
Fluid		Air(to be filte	red by 40µm f	ilter element)	
Operating programs	(Þ10: 0.2~0.7N	1Pa(29~100ps	si)(2.0~7.0bar	.)
Operating pressure	Ot	hers: 0.15~0.1	7MPa(22~100	psi)(1.5~7.0b	ar)
Temperature °C			-20~70		
Lubrication	Cylinder: Not required; Gripper jaws: Lubricate grease				
Cushion type	Bumper				
Max. frequency	60(c.p.m)				
Repeatability	±0.2mm				
Gripping force [Note1]	0.16N.m	0.55N.m	1.10N.m	2.30N.m	5.00N.m
Open or close angle	Close: -2° ~ -5° Open: 180° ± 2°				
Port size	M5×0.8				
Sensor switches [Note2]	CMSH\DMSH\EMSH				

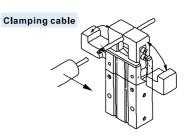
[Note1] The gripping force is the value when the operating pressure is 0.5Mpa.

 $[Note2] \, Sensor \, switch \, should \, be \, ordered \, additionally, \, please \, refer \, to \, P362 \, for \, detail \, of \, sensor \, switch. \, and \, such a such$

Example

Screw down



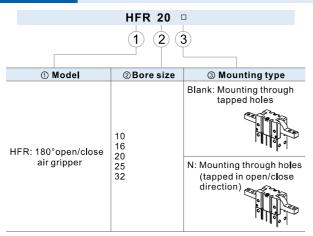




HFR Series



Ordering code

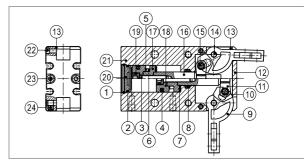


[Note] HFR series are all attached with magnet.

Symbol

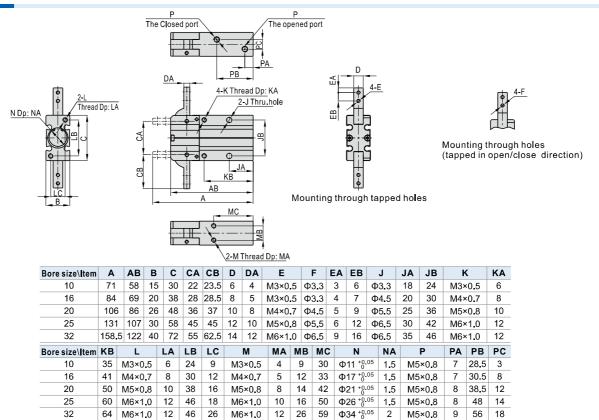


Inner structure and material of major parts



NO.	Item	Material	NO.	Item	Material
1	C clip	Spring steel	12	Front cover	Aluminum alloy
2	O-ring	NBR	13	Sheet metal	Stainless steel
3	Countersink	Carbon steel	14	Pin	Stainless steel
3	screw	Carbon steel	15	Pin	Stainless steel
4	Piston seal	NBR	16	Piston rod	Stainless steel
5	Magnet washer	NBR	17	Magnet holder	Aluminum alloy
6	Magnet	Sintered metal (Neodymium-iron-ioron)	18	Piston	Aluminum alloy
O	6 Magnet		19	O-ring	NBR
7	Bumper	TPU	20	Back cover	Aluminum alloy
8	Rod packing	NBR	21	Body	Aluminum alloy
9	Gripping jaws	Stainless steel	22	Pin	Stainless steel
10	Pin sheath	Stainless steel	23	Countersink screw	Carbon steel
11	Push block	Stainless steel	24	Countersink screw	Carbon steel

Dimensions





HFR Series

How to select product

- 1. Confirmation of effective gripping force
 - 1.1) Though the coefficient of friction between the attachments and the workpiece is different. select a gripping force which is 10 to 20 times greater than the workpiece weight.
 - 1.2) If high acceleration or impact forces are encountered during motion, a further margin of safety should be considered.

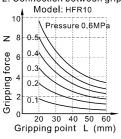
Example: When the workpiece weight is 0.05 and the gripping point distance L is 30mm, the operating pressure will be 5kgf/cm².

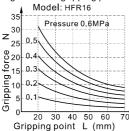
Effective gripping force=0.05kg×20 times×9.8m/s²=more than 10N Model selection: HFR16 is recommended. The effective gripping force is 17N,

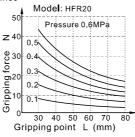
which is 20 times greater than the set value of gripping force.

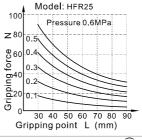
1.3) The finger thrust is expressed as F, when both fingers and attachments are in full contact with the workpiece as shown in the figure below.

2. Connection between gripping force and gripping point distance

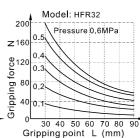






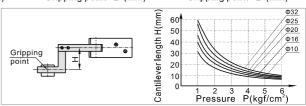


L: Gripping point



F: Single finge

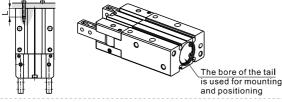
- 3. The selection of the gripping point
 - 3.1) Please select the gripping point within the limited field shown left. Over the limits, gripping jaws would be subjected to excessive torque loads, and lead to short life of the air gripper.
 - 3.2) In the allowable range of gripping point, it is better to design for short and light fittings. If the fittings are long and heavy, the inertia force when the finger is open and close will become larger, and the performance of gripping jaw will be degraded, at the same time it will affect the life.



Installation and application

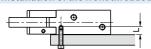
- 1. Due to the abrupt changes, the pressure is low, which will lead to the decrease of the gripping force and falling of the work-pieces. In order to avoid the harm to the human body and damage to the equipment, anti-dropping device must be equipped.
- 2. Don't use the air gripper under strong external force and impact force.
- 3. When install and fix the air gripper, avoid falling down, collision and damage.
- 4. When fixing the gripping jaw parts, don't twist the gripping jaw.
- 5. There are several kinds of installation method, and the torque of fastening screw must be within the prescribed moment range shown in the below chart. If the locking moment is too large, it will cause the dysfunctional. If the locking moment is too small, it will cause the position deviation and fall.

Tail installation type



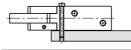
	The bolts	Max. locking	Max.screwed	The aperture of the	
size	type	moment	depth	positioning bore	positioning bore
10	M3×0.5	1.0N.m	6mm	Ф11mmH9	1.5mm
16	M4×0.7	2.0N.m	8mm	Ф17mmH9	1.5mm
20	M5×0.8	4.5N.m	10mm	Ф21mmH9	1.5mm
25	M6×1.0	7.0N.m	12mm	Ф26mmH9	1.5mm
32	M6×1.0	7.0N.m	14mm	Ф34mmH9	2.0mm

The installation of the front threaded hole



Bore size	The bolts type	Max. locking moment(Nm)	Max. screwed depth(mm)
10	M3×0.5	1.0	6
16	M4×0.7	2.0	8
20	M5×0.8	4.5	10
25	M6×1.0	7.0	12
32	M6×1.0	7.0	14

The installation of the front through hole



Bore size	The bolts type	Max. locking moment(Nm)
10	M3×0.5	1.0
16	M4×0.7	2.0
20	M5×0.8	4.5
25	M6×1.0	7.0
32	M6×1.0	7.0





		Max. locking	Max. screwed
size	type	moment(Nm)	depth(mm)
10	M3×0.5	0.6	4
16	M4×0.7	1.5	5
20	M5×0.8	3.5	8
25	M6×1.0	6.0	10
32	M6×1.0	6.0	12

- $\textbf{6.} \textbf{The installation method of the gripping jaw fittings.} \ \textbf{When install the gripping jaw}$ fittings, you have to pay particular attention that you can only hold the gripping jaw by using spanner, and then lock the screws with allen wrench. Never clamp the body directly and then lock the screws, otherwise the parts will be easily
- 7. Other contents of installation and operation are the same with those of HFY. Refer to the "Installation and Operation" instruction of HFY.

Bore size	The bolts type	Max. locking moment(Nm)
10	M3×0.5	0.6
16	M3×0.5	0.6
20	M4×0.7	0.8
25	M5×0.8	1.5
32	M6×1.0	3.0

